

Optimal Incentive Contract with Costly and Flexible Monitoring

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Motivation

Choice of monitoring technology has significant impact on employee productivity.

Standard agency models take the monitoring technology as exogenously given.

Need strong assumptions to justify

- 1 Simple and intuitive contracts;
- 2 Heterogeneity in managerial practices.

Preview

A principal-agent model with flexible and costly monitoring:

- **Flexibility:** specify the qualitative and quantitative natures of the monitoring technology;
- **Cost:** increasing in the entropy of the agent's compensation.

Endogenize the choice of monitoring technology as part of the contract design problem.

Use factors that affect the monitoring cost to explain

- Simple and intuitive contracts;
- Heterogeneity in human resource practices.

Agenda

- 1 Baseline model
- 2 Extensions
- 3 Conclusion

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Setup

A risk-neutral principal and a risk-averse agent.

Agent payoff $u(w) - c(a)$:

- Consumption $w \geq 0$, $u(0) = 0$, $u' > 0$, $u'' < 0$;
- Effort $a \in \{0, 1\}$, $c(1) = c > c(0) = 0$.

Each effort level a generates a probability space (Ω, Σ, P_a) .

Principal's goal: elicit high effort from the agent.

Incentive Contract

A pair of monitoring technology \mathcal{P} and wage scheme $w(\cdot)$:

- 1 \mathcal{P} : a partition of Ω whose elements belong to Σ ;
- 2 $w : \mathcal{P} \rightarrow \mathbb{R}_+$.

Timeline:

- Parties commit to $\langle \mathcal{P}, w(\cdot) \rangle$;
- The agent privately exerts $a \in \{0, 1\}$;
- Nature draws $\omega \in \Omega$ according to P_a ;
- $A(\omega) \in \mathcal{P}$ is publicly realized;
- The principal pays the promised wage $w(A(\omega))$.

Incentive Contract (Cont.)

The contract defines a signal X and a random wage W .

For each effort level a and $A \in \mathcal{P}$:

- X takes value A with prob. $P_a(\omega \in A)$;
- W equals $w(A)$ with prob. $P_a(\omega \in A)$.

Monitoring Cost and Total Cost

Monitoring cost for each given a :

$$\mu \cdot H_a(W)$$

- 1 $H_a(W)$: entropy of the random wage.
- 2 $\mu > 0$: cost and benefit of monitoring the agent.

Total cost for each given a :

$$\underbrace{\mathbb{E}_a[W]}_{\text{incentive cost}} + \underbrace{\mu \cdot H_a(W)}_{\text{monitoring cost}}$$

Detect Deviation

For each $A \in \Sigma$, define

$$z(A) = 1 - \underbrace{\frac{dP_0}{dP_1}(A)}_{\text{likelihood ratio}}$$

A contract is incentive compatible for the agent if

$$\int_{A \in \mathcal{P}} u(w(A))z(A)dP_1 \geq c$$

Optimal Incentive Contract

The optimal incentive contract $\langle \mathcal{P}^*, w^*(\cdot) \rangle$ solves

$$\begin{aligned} \min_{\langle \mathcal{P}, w(\cdot) \rangle} \mathbb{E}_1[W] + \mu \cdot H_1(W) \\ \text{s.t. (IC) and (LL)} \end{aligned}$$

Benchmark: Exogenous Monitoring Technology

Standard agency models take \mathcal{P} as exogenously given and solve for

$$\min_{w: \mathcal{P} \rightarrow \mathbb{R}_+} \mathbb{E}_1[W], \text{ s.t. (IC) and (LL)}$$

Denote the solution by $w^*(\cdot; \mathcal{P})$.

Lemma 1.

For any given \mathcal{P} , there exists $\lambda > 0$ such that for each $A \in \mathcal{P}$, $u'(w^(A; \mathcal{P})) = \frac{1}{\lambda z(A)}$ if and only if $w^*(A; \mathcal{P}) > 0$.*

Increasing Wage Scheme and MLRP

Definition 1.

Suppose \mathcal{P} is totally ordered under \preceq . Then the distributions of the signal induced by \mathcal{P} satisfy the monotone likelihood ratio property if any $A, A' \in \mathcal{P}$ such that $A \preceq A'$, we have $z(A) < z(A')$.

Lemma 2.

Suppose \mathcal{P} is totally ordered under \preceq . Then $w^(\cdot; \mathcal{P})$ is increasing if and only if the distributions of the signal induced by \mathcal{P} satisfy MLRP.*

Why May MLRP Fail?

For an arbitrary monitoring technology,

- 1 \mathcal{P} may not be totally ordered, e.g., multi-source feedback;
- 2 Even if \mathcal{P} is totally ordered, MLRP is still a strong property.

Optimal Contract with Costly and Flexible Monitoring

Theorem 1.

For any $\mu > 0$,

- (i) $\mathcal{P}^* = \{A_1, A_2, \dots, A_n\}$ for some $n \in \mathbb{N}$;
- (ii) $z(A_1) < z(A_2) < \dots < z(A_n)$;
- (iii) $w^*(A_1) = 0 < w^*(A_2) < \dots < w^*(A_n)$.

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 - Multi-agent
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Multiple Tasks

A risk-neutral principal and a risk-averse agent.

The agent can exert $a_i \in \{0, 1\}$ in each of two tasks $i = 1, 2$.

Each effort profile $\vec{a} \in \{0, 1\}^2$ generates $(\Omega, \Sigma, P_{\vec{a}})$.

Principal's goal: elicit high effort in both tasks.

Detect Deviation

For each $A \in \Sigma$ and each $\vec{a} \in \{10, 01, 00\}$, define

$$z_{\vec{a}}(A) = 1 - \frac{dP_{\vec{a}}(A)}{dP_{11}(A)}$$

A contract is incentive compatible for the agent if for each $\vec{a} \in \{10, 01, 00\}$,

$$\int_{A \in \mathcal{P}} u(w(A)) z_{\vec{a}}(A) dP_{11} \geq c(11) - c(\vec{a})$$

Optimal Multi-Task Contract with Costly and Flexible Monitoring

Theorem 2.

For each $\mu > 0$,

- (i) $\mathcal{P}^* = \{A_1, \dots, A_n\}$;
- (ii) $w^*(A_1) = 0 < w^*(A_2) < \dots < w^*(A_n)$;
- (iii) There exist $\lambda_{\vec{a}}, \vec{a} \in \{10, 01, 00\}$, such that for all $k = 2, \dots, n$,

$$u'(w^*(A_k)) = \frac{1}{\sum_{\vec{a}} \lambda_{\vec{a}} z_{\vec{a}}(A_k)}$$

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- ① Baseline model
- ② Extensions:
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 - Multi-agent
- ③ Conclusion

Multiple Agents

A risk-neutral principal and two risk-averse agents $i = 1, 2$.

Each agent i exerts $a_i \in \{0, 1\}$.

Each a_i independently generates $(\Omega, \Sigma, P_{a_i})$, where

- $\Omega = \{0, 1\}$, $\Sigma = \{\emptyset, \{0\}, \{1\}, \{0, 1\}\}$;
- $P_1(1) = p \in (0, 1)$ and $1 - \frac{dP_0(1)}{dP_1(1)} = z \in (0, 1)$.

Each $\vec{a} = (a_1, a_2)$ generates $(\Omega \times \Omega, \Sigma \otimes \Sigma, P_{a_1} \times P_{a_2})$.

Incentive Contract

Principal's goal: elicit high effort from both agents.

A monitoring technology \mathcal{P} and a wage scheme $\vec{w}(\cdot)$:

- 1 \mathcal{P} : a partition of $\Omega \times \Omega$ whose elements belong to $\Sigma \otimes \Sigma$;
- 2 $\vec{w} : \mathcal{P} \rightarrow \mathbb{R}_+^2$.

Individual Reward

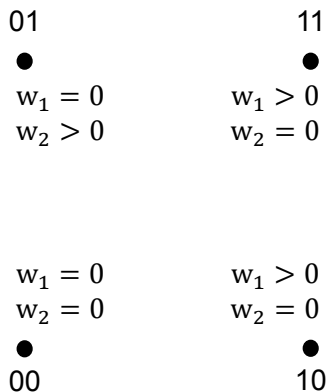


Figure: Γ_4

Tournament

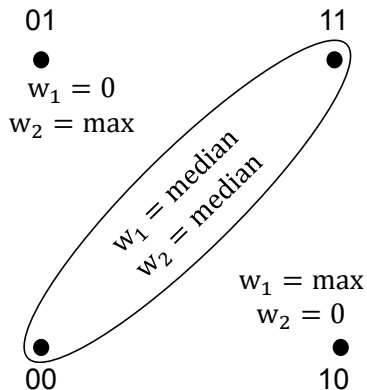


Figure: Γ_{3b}

Group Compensation

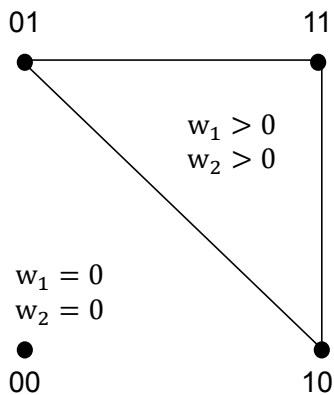


Figure: Γ_{2a}

Group Compensation

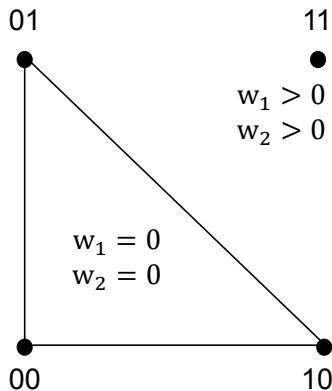


Figure: Γ_{2b}

Optimal Multi-Agent Contract

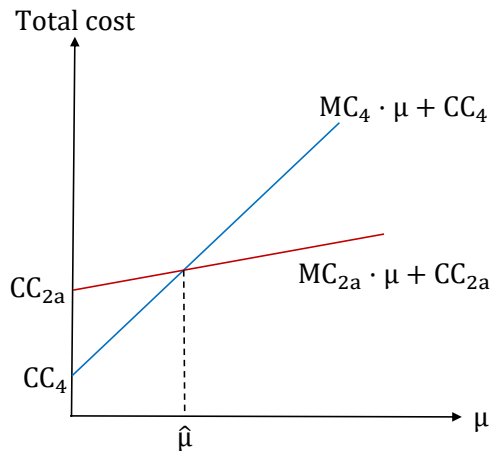


Figure: Individual reward vs. group compensation

Result

- ① Difference in μ yields various kinds of incentive schemes.
- ② Lack of individual performance appraisal when μ is big.

Explain variation in managerial practices by factors that affect μ :

- **Cost:** information technology, labor market regulation, tacit knowledge transfer;
- **Benefit:** human capital share, product market competition.

Conclusion

A principal-agent model with costly and flexible monitoring.

Endogenize the choice of monitoring technology.

Use factors that affect the monitoring cost to explain

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